# **AITTAC**

## Linear Guide(2023B) Europe

- **OLSH Series Standard Linear Guide**
- ●LSD Series Low Profile Type Linear Guide
- LRW Series Miniature Linear Guide (Widened)
- LRM Series Miniature Linear Guide
- **LGC Series Crossed Roller Way**



## **AirTAC** • Linear Guide

## **Products Catalog-2023B**

LSH Series Standard Linear Guide
 LSD Series Low Profile Type Linear Guide
 LRW Series Miniature Linear Guide (Widened)
 LGC Series Crossed Roller Way



## **AirTAC International Group**

### **Corporate Profile**



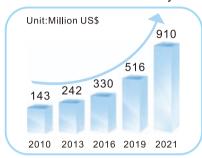
2019:

AirTAC Ningbo the second Production base established

2018:

AirTAC USA established

Annual revenue over the years





2016-2018: AirTAC(Guangdong/Tianjin /Fujian) Intelligent Company established



2012-2015:

AirTAC Singapore, AirTAC Japan, AirTAC Malaysia, AirTAC Thailand established



2015: AirTAC (Jiangsu) established



2010:

AirTAC IPO In Taiwan (Stock code:1590.TW)







2008: AirTAC Italy established

2016:

New production base of AirTAC Tainan established

2002: AirTAC Ningbo

established

1988: AirTAC Taiwan established



1998: AirTAC Guangdong established



# A

## **AirTAC International Group**

## **Corporate Profile**



#### 2019

AirTAC Ningbo the second Production base established

AirTAC Ningbo the second Production base Land area: 266,667m<sup>2</sup>

Add: No.89, Nandu Rd., Fenghua District, Ningbo, Zhejiang, China

#### 2016

New production base of AirTAC Tainan established

Taiwan Tainan Production base
Land area: 71,333m²
Add: No.28, Kanxi Rd., Xinshi District, Tainan, Taiwan



#### 2002

AirTAC Ningbo established

AirTAC Ningbo the first Production base Land area: 240,000m² Add: No.88, Siming E. Rd., Fenghua District, Ningbo, Zhejiang, China

#### 1998

AirTAC Guangdong established

AirTAC Guangdong Land area: 26,667m² Add: No.7, Kaixuan Rd., Nanhai District, Foshan, Guangdong, China





# A

## **AirTAC International Group**

## **Manufacturing Equipment**

Injection molding Equipment Array (Japan-made)



Cryogenic-treatment Equipment





Machining Equipment Array(Japan-made)

EFD Induction Hardening Equipment (Norway-made)



IPSEN Carburising Equipment(Germany-made)



Grinding Machine Array





Auto-assembly Line





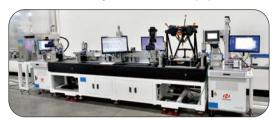
## **AirTAC International Group**

### Detection Equipment R&D Experimental Equipment

Zeiss Coordinate Measuring Machine(CMM)(Germany-made)



Rail Accuracy Classification Equipment



Chemical Analysis Equipment



Metallographic Analysis (Japan-made)

Hardness Detection Equipment (Netherlands-made)



Linear guide accuracy Measurement Equipment



Linear guide life span Test Equipment

Linear guide complex performance Test Equipment

Renishaw Equator



# A

## **AirTAC International Group**

### **Global Network of Marketing&Service**

AirTAC International Group has more than 100 direct sales branches/sales sections in Chinese mainland, and thousands of distributors around the world, mainly located in Europe, the United States and Asia, etc., forming a perfect sales network and after-sales service system, which can provide customers with convenient services at any time.



#### Overseas Market

- ●USA
- Japan
- ●UK
- France
- Finland
- Germany
- ●Thailand
- ●Korea
- Australia
- ●Mexico
- Argentina
- South Africa

- Italy
- Singapore
- Malaysia
- ●Greece
- Sweden
- Denmark
- India
- Brazil
- Netherlands
- Sri Lanka
- ●Colombia
- Jordan

- VietNam
- Indonesia
- Israel
- •Turkey
- ●Kuwait
- ●Austria
- •Saudi Arabia
- ●Peru
- ●Canada
- ●Iran
- ●Syria

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## Linear Guide——Index

**Linear Guide Selection** P2

#### LSH Series Standard Linear Guide

P10

- Standard type(N) and Long type(L) are available, one block and two blocks type are available
- ●Square type(H), Flange type top-mount(F1), Flange type bottom-mount(F2), Flange type top or bottom mount(F3) block are available

●LSH15、20、25、30、35、45;

●Block with double oil scrapers(DD)

or oil scraper+metal scraper(ZZ) type are available



#### LSD Series Low Profile Type Linear Guide

●Short type(S) and Standard type(N) are available, one block and two blocks type are available

- ●Square type(H), Flange type top-mount(F1), Flange type bottom-mount(F2), Flange type top or bottom mount(F3) block are available
- ●LSD15、20、25、30、35;
- Block with double oil scrapers(DD) or oil scraper+metal scraper(ZZ) type are available



#### LRW Series Miniature Linear Guide (Widened)

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- ●Standard type(N) and Long type(L) are available, one block and two blocks type are available
- ●LRW7、9、12、15



#### **LRM Series Miniature Linear Guide**

●Standard type(N) and Long type(L) are available, one block and two blocks type are available

●LRM5、7、9、12、15。



#### **LGC Series Crossed Roller Way**

Accuracy class: High-accuracy and precision grade are available

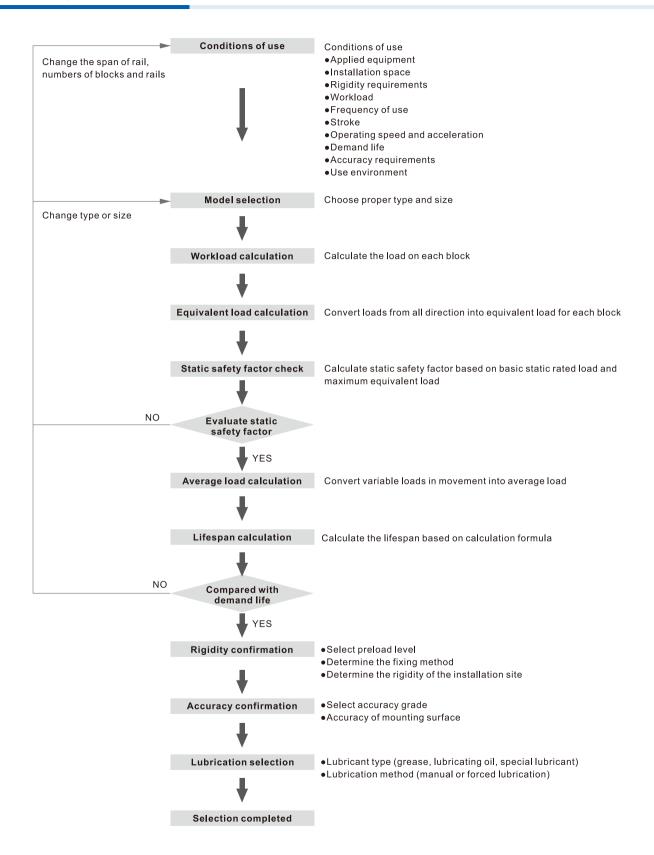
- Three-row type and four-row type are available
- ●Roller diameter: Φ1.5、Φ2、Φ3、Φ4、Φ6



P27



#### How to select Linear Guide





#### **Load Capacity and Rating Life**

#### 1. Basic static load rating (C<sub>0</sub>)

When a linear guide absorbs a large force or impact in a static or low-speed movement, it will cause permanent deformation either on rollers and groove.

When sum of deformation on groove and rollers exceeds a certain limit, it will affect the smoothness of its linear movement.

Basic static load rating is defined as the magnitude of a given stress applied at where the stress is the biggest caused the sum of permanent deformation on groove and roller is 1/10000 of the diameter of the rollers.

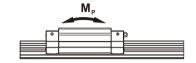
#### 2. Allowable static moment(M<sub>0</sub>)

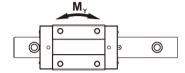
When torque is applied on a linear guide, rollers in the both ends of block will endure the major stress force.

Allowable static moment is defined as a given moment applied and raised stress force on linear guide which will cause sum of permanent deformation on groove and roller is 1/10000 of the diameter of the rollers.

Static moment is defined in three directions as M<sub>P</sub>, M<sub>y</sub>, M<sub>B</sub>.







#### 3. Static safety factor(f<sub>c</sub>)

During vibration, impact or sudden start and stop, the inertia force or torque will raise huge loads on linear guide. For this kind of situation, it is necessary to put static safety factor into consideration. Static safety factor is a ratio of the basic statics load rating to the calculated working load as shown in following formula. The reference of static safety factor for different conditions is shown in following table:

Use machinery	Load condition	$f_{ m s}$
General industrial machinery	General load conditions	1.0~1.3
	When there is vibration or shock	2.0~3.0
Machine tool	General load conditions	1.0~1.5
	When there is vibration or shock	2.5~7.0

$$f_s = \frac{C_\theta}{P} \text{ or } f_s = \frac{M_\theta}{M}$$
  
 $f_s$ : Static safety factor

 $C_o$ : Basic static load rating (N)

 $M_{\scriptscriptstyle 0}$ : Allowable static moment  $(N \cdot m)$ P: Calculation load (N)

M: Calculation moment  $(N \cdot m)$ 

#### 4. Basic dynamic load rating(C)

Basic Dynamic Load rating is defined as the maximum allowable load and can be applied on the same specification of linear guides. This will result in a nominal life of 50 KM operation for linear guide.

#### 5. Life calculation

#### Life

When a linear guide is with bearings loaded during operation, the groove and rollers will constantly endure stress force. Once reaching fatigue, the surface will peel off and damage. The life of a given linear guide is defined as the moving distance of a linear guide in which peeling occurs due to fatigue.

#### Nominal life

Actual lifespan of linear guide varies enormously. The lifespan of each guide can be different even though they come from the same product batch under the same condition. Therefore, nominal life is usually chosen as bench mark to evaluate lifespan. Nominal life is defined as the moving distance for 90% of linear guides from the same production batch which can perform under the same working condition without peeling.

#### Life factor

#### 1. Hardness factor( $f_{\scriptscriptstyle \rm H}$ )

Surface hardness of rollers must be HRC 58~62. A softer hardness will reduce load-bearing performance and static load rating. Therefore allowable moment must be multiplied by a hardness factor as correlation shown on the right chart.

Our hardness requirement for linear guide is HRC58~62, therefore  $f_{\rm H}$  = 1.0.

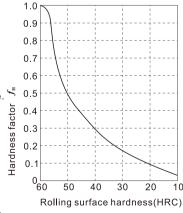
#### 2. Temperature factor( $f_{\scriptscriptstyle { m T}}$ )

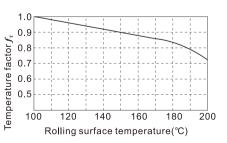
High temperature environment will affect lifespan of the linear guide. Therefore, static load rating and allowable moment must be multiplied by a temperature factor  $f_{\rm T}$  as correlation shown on the right graph.

Certain parts of our linear guide are made of plastic and rubber, hence working in temperature higher than 100°C is not recommended.

#### 3. Load factor( $f_*$ )

Although loads on a given linear guide can be calculated, it will usually come with vibration or hitting in actual use. This makes actual loads higher than calculated figure. Hence, in heavy vibration or hitting condition, please divide basic dynamic load rating (C) by following empirical load factor.





Working Conditions	Use speed	$f_{ m w}$
Smooth without impact	V≤15m/min	1.0~1.2
Common impact and vibration	15m/min < V≤60m/min	1.2~1.5
Moderate impact and vibration	60m/min < V≤120m/min	1.5~2.0
Strong impact and vibration	V≥120m/min	2.0~3.5



#### 4. Contact factor( f<sub>c</sub>)

When multiple blocks on the linear guide are used in close contact with each other, it is difficult to evenly distribute the load due to moment torque or the accuracy of the mounting surface. Hence, when using multiple blocks in close contact, multiply the basic load rating (C or C0) by the corresponding contact factor in the table below

Note: Take into account the contact factor in the table below if uneven load distribution is expected in a large machine.

Number of blocks used in close contact		3	4	5	≥6	Normal use
Contact factor f <sub>c</sub>	0.81	0.72	0.66	0.61	0.6	1

#### •Calculation of nominal life(L)

The nominal life will vary based on applied load. Hardness and working temperature will also have great effects on lifespan of a linear guide. Putting all factors into consideration, nominal life can be calculated by following formula:

L: Nominal life (km)

$$L = \left(\frac{f_H \times f_T \times f_C}{f_W} \times \frac{C}{P}\right)^3 \times 50Km$$

C: Basic dynamic load rating (N)

P: Workload (N)

 $f_{\rm w}$ : Load factor

 $f_{\!\scriptscriptstyle H}$  : Hardness factor

 $\mathbf{f}_{\scriptscriptstyle T}$  : Temperature factor

f.: Contact factor

#### •Calculation of service life time(L<sub>h</sub>)

If stroke length and repeating time are known, service life time  $(L_h)$  can be derived based on rated life (L)

$$L_h = \frac{L \times 10^3}{2 \times l_s \times n_1 \times 60}$$

 $L_h$ : Service life time (hr)

L: Rated life (km)

 $l_s$ : Stroke length (m)

 $n_i$ : Rounds per minute

 $(min^{-1})$ 

#### Calculation of working load

Load effect on a linear guide will be affected by its center of mass, position of thrust and inertia force occurring by acceleration when starting or stopping, etcetera. Therefore, most applications of working conditions must be put into consideration in order to acquire accurate nominal life.

#### Working load calculation

Туре	Operation condition	Load on each block
Horizontal use uniform motion Or at rest		$P_{i} = \frac{F}{4} + \frac{Fl_{3}}{2l_{1}} - \frac{Fl_{4}}{2l_{2}}$ $P_{2} = \frac{F}{4} - \frac{Fl_{3}}{2l_{1}} - \frac{Fl_{4}}{2l_{2}}$ $P_{3} = \frac{F}{4} - \frac{Fl_{3}}{2l_{1}} + \frac{Fl_{4}}{2l_{2}}$ $P_{4} = \frac{F}{4} + \frac{Fl_{3}}{2l_{1}} + \frac{Fl_{4}}{2l_{2}}$
Horizontal cantilever use uniform motion Or at rest	P <sub>1</sub> P <sub>2</sub> P <sub>3</sub>	$P_{i} = \frac{F}{4} + \frac{Fl_{s}}{2l_{i}} + \frac{Fl_{s}}{2l_{2}}$ $P_{2} = \frac{F}{4} - \frac{Fl_{s}}{2l_{i}} + \frac{Fl_{s}}{2l_{2}}$ $P_{3} = \frac{F}{4} - \frac{Fl_{s}}{2l_{i}} - \frac{Fl_{s}}{2l_{2}}$ $P_{4} = \frac{F}{4} + \frac{Fl_{s}}{2l_{i}} - \frac{Fl_{s}}{2l_{2}}$
Vertical use uniform motion Or at rest	$P_{i1}$ $P_{i1}$ $P_{i2}$ $P_{i3}$ $P_{i4}$ $P_{i5}$ $P$	$P_{i}=P_{2}=P_{3}=P_{4}=rac{Fl_{3}}{2l_{1}}$ $P_{i,\tau}=P_{2,\tau}=P_{3,\tau}=P_{4,\tau}=rac{Fl_{4}}{2l_{1}}$
Wall-mounted use uniform motion Or at rest	$\begin{array}{c} I_1 & P_{2T} \\ P_2 & P_2 \\ P_{3T} & P_{3T} \end{array}$	$P_{1}=P_{2}=P_{3}=P_{4}=\frac{Fl_{4}}{2l_{2}}$ $P_{1T}=P_{4T}=\frac{F}{4}+\frac{Fl_{3}}{2l_{1}}$ $P_{2T}=P_{3T}=\frac{F}{4}-\frac{Fl_{3}}{2l_{1}}$



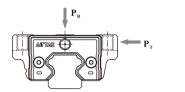
Туре	Operation condition	Load on each block
Lateral Slope	$P_3$ $P_3$ $P_4$ $P_5$	$\begin{split} P_{i} &= \frac{F \cdot \cos\theta}{4} + \frac{F \cdot \cos\theta \cdot l_{i}}{2 \cdot l_{i}} - \frac{F \cdot \cos\theta \cdot l_{i}}{2 \cdot l_{i}} + \frac{F \cdot \sin\theta \cdot h_{i}}{2 \cdot l_{i}} \\ P_{2} &= \frac{F \cdot \cos\theta}{4} - \frac{F \cdot \cos\theta \cdot l_{i}}{2 \cdot l_{i}} - \frac{F \cdot \cos\theta \cdot l_{i}}{2 \cdot l_{i}} + \frac{F \cdot \sin\theta \cdot h_{i}}{2 \cdot l_{i}} \\ P_{3} &= \frac{F \cdot \cos\theta}{4} - \frac{F \cdot \cos\theta \cdot l_{i}}{2 \cdot l_{i}} + \frac{F \cdot \cos\theta \cdot l_{i}}{2 \cdot l_{i}} - \frac{F \cdot \sin\theta \cdot h_{i}}{2 \cdot l_{i}} \\ P_{4} &= \frac{F \cdot \cos\theta}{4} + \frac{F \cdot \cos\theta \cdot l_{i}}{2 \cdot l_{i}} + \frac{F \cdot \cos\theta \cdot l_{i}}{2 \cdot l_{i}} - \frac{F \cdot \sin\theta \cdot h_{i}}{2 \cdot l_{i}} \\ P_{17} &= P_{47} = \frac{F \cdot \sin\theta}{4} + \frac{F \cdot \sin\theta \cdot l_{i}}{2 \cdot l_{i}} \\ P_{27} &= P_{37} = \frac{F \cdot \sin\theta}{4} - \frac{F \cdot \sin\theta \cdot l_{i}}{2 \cdot l_{i}} \end{split}$
Axial Slope		$\begin{split} P_{i} &= \frac{F \cdot cos\theta}{4} + \frac{F \cdot cos\theta \cdot l_{s}}{2 \cdot l_{i}} - \frac{F \cdot cos\theta \cdot l_{s}}{2 \cdot l_{s}} + \frac{F \cdot sin\theta \cdot h_{i}}{2 \cdot l_{i}} \\ P_{i} &= \frac{F \cdot cos\theta}{4} - \frac{F \cdot cos\theta \cdot l_{s}}{2 \cdot l_{i}} - \frac{F \cdot cos\theta \cdot l_{s}}{2 \cdot l_{s}} - \frac{F \cdot sin\theta \cdot h_{i}}{2 \cdot l_{i}} \\ P_{i} &= \frac{F \cdot cos\theta}{4} - \frac{F \cdot cos\theta \cdot l_{s}}{2 \cdot l_{i}} + \frac{F \cdot cos\theta \cdot l_{s}}{2 \cdot l_{s}} - \frac{F \cdot sin\theta \cdot h_{i}}{2 \cdot l_{i}} \\ P_{i} &= \frac{F \cdot cos\theta}{4} + \frac{F \cdot cos\theta \cdot l_{s}}{2 \cdot l_{i}} + \frac{F \cdot cos\theta \cdot l_{s}}{2 \cdot l_{s}} + \frac{F \cdot sin\theta \cdot h_{i}}{2 \cdot l_{i}} \\ P_{i,T} &= P_{i,T} = + \frac{F \cdot sin\theta \cdot l_{s}}{2 \cdot l_{i}} \\ P_{2T} &= P_{j,T} = - \frac{F \cdot sin\theta \cdot l_{s}}{2 \cdot l_{i}} \end{split}$
Use horizontally with inertial force		When accelerating When decelerating $P_{i} = P_{4} = \frac{mg}{4} - \frac{m \cdot a_{i} \cdot l_{s}}{2 \cdot l_{i}} \qquad P_{i} = P_{4} = \frac{mg}{4} + \frac{m \cdot a_{i} \cdot l_{s}}{2 \cdot l_{i}}$ $P_{2} = P_{3} = \frac{mg}{4} + \frac{m \cdot a_{i} \cdot l_{s}}{2 \cdot l_{i}} \qquad P_{2} = P_{3} = \frac{mg}{4} - \frac{m \cdot a_{i} \cdot l_{s}}{2 \cdot l_{i}}$ $P_{i,\tau} = P_{2\tau} = P_{s,\tau} = P_{s\tau} = \frac{m \cdot a_{i} \cdot l_{s}}{2 \cdot l_{i}} \qquad P_{i,\tau} = P_{2\tau} = P_{s\tau} = P_{s\tau} = \frac{m \cdot a_{s} \cdot l_{s}}{2 \cdot l_{i}}$ At constant speed $P_{i} = P_{2} = P_{3} = P_{4} = \frac{mg}{4}$
Use Vertically with inertial force	$V(m/s)$ $A_n = (\frac{V}{t_n})$ $P_{2T}$	When accelerating $P_{i} = P_{2} = P_{3} = P_{4} = \frac{m \cdot (g + a_{i}) \cdot l_{3}}{2 \cdot l_{i}}$ $P_{i,T} = P_{2,T} = P_{3,T} = P_{4,T} = \frac{m \cdot (g + a_{i}) \cdot l_{4}}{2 \cdot l_{i}}$ When decelerating $P_{i} = P_{2} = P_{3} = P_{4} = \frac{m \cdot (g - a_{3}) \cdot l_{3}}{2 \cdot l_{i}}$ $P_{i,T} = P_{2,T} = P_{3,T} = P_{4,T} = \frac{m \cdot (g - a_{3}) \cdot l_{4}}{2 \cdot l_{i}}$ At constant speed $P_{i} = P_{2} = P_{3} = P_{4} = \frac{mg \cdot l_{3}}{2 \cdot l_{i}}$ $P_{i,T} = P_{2,T} = P_{3,T} = P_{4,T} = \frac{mg \cdot l_{4}}{2 \cdot l_{i}}$



#### Calculation of equivalent load

A block can bear force as well as torque from all axial and radial directions. When multiple loads are applied, these loads can be combined as an equivalent axial and radial load for the calculation of nominal life or static safety factor.

Our linear guide can bear loads in four directions, up, down, left, and right. So when using linear slides, it may be subjected to vertical load (Ps) and lateral load (P₁) at the same time. When two or more linear guides are used, the equivalent load (P₂) can be converted according to the following formula.



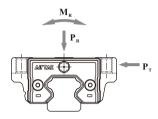
 $P_{\scriptscriptstyle E} = |P_{\scriptscriptstyle R}| + |P_{\scriptscriptstyle T}|$  $P_{\scriptscriptstyle E}$ : Equivalent load

(N)

 $P_{\scriptscriptstyle R}$ : Radial load (N)

 $P_{\tau}$ : Lateral load (N)

In the case of single linear guide, equivalent load must take torque into account, see following formula.



 $P_{\scriptscriptstyle E} = |P_{\scriptscriptstyle R}| + |P_{\scriptscriptstyle T}| + C_{\scriptscriptstyle \theta} \frac{|M|}{M_{\scriptscriptstyle R}}$   $P_{\scriptscriptstyle E}:$  Equivalent load

(N)

 $P_{\scriptscriptstyle R}$ : Radial load (N)

 $P_{\scriptscriptstyle T}$ : Lateral load (N)

Ca: Basic static load rating (N)

M: Calculated torque  $(N \cdot m)$  $M_{\scriptscriptstyle R}$ : Allowable static moment  $(N \cdot m)$ 

#### Calculation of average load

The real-time acting load for a block during movement is always variable. One can derive average load for the use of rated life calculation based on different applications. Average load when rollers are steel ball is as follows:

$$P_{m} = e\sqrt{\frac{1}{L} \cdot \sum_{n=1}^{n} \left( P_{n}^{e} \cdot L_{n} \right)}$$

P...: Average load

(N)

P.: Variable load

(N)

L: Total Working Distance

(mm)

 $L_n$ : Moving distance when load  $P_n$  applied (mm)

e: Exponent (for steel ball: 3)

#### Average load calculation example

Varying load type	Average load calculation
Interval Variable Load $\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$P_{m} = e\sqrt{\frac{1}{L} \cdot \left(P_{i}^{e} \cdot L_{i} + P_{i}^{e} \cdot L_{z} + \dots + P_{n}^{e} \cdot L_{n}\right)}$ $P_{m} : \text{Average load} \qquad (N)$ $P_{s} : \text{Variable load} \qquad (N)$ $L : \text{Total Working Distance} \qquad (mm)$ $L_{n} : \text{Moving distance when load } P_{n} \text{ applied} \qquad (mm)$ $e : \text{Exponent (for steel ball: 3)}$
Monotonic variable load $\begin{array}{c} P_{max} \\ \hline P_{min} \\ \hline \end{array}$ Total working distance(L)	$P_{m} \approx \frac{1}{3} \left( P_{min} + 2 \cdot P_{max} \right)$ $P_{m} : \text{Average load} \qquad (N)$ $P_{min} : \text{Minimum load} \qquad (N)$ $P_{max} : \text{Maximum load} \qquad (N)$

## AITTAL

#### **Linear Guide Selection**

Varying load type	Average load calculation		
Sinusoidal variable load $P_{max}$ $P_{m}$ $P_{m}$ $Total working distance(L)$	$P_{m}pprox 0.65 \cdot P_{max}$ $P_{m}$ : Average load (N) $P_{max}$ : Maximum load (N)		
P <sub>max</sub> P <sub>m</sub> Total working distance(L)	$P_{m} \approx 0.75 \cdot P_{max}$ $P_{m}$ : Average load (N) $P_{max}$ : Maximum load (N)		

#### Calculation example

#### Conditions of Use

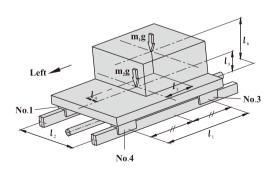
Model:  $LSH30HL2X2520S20BP-M6(2\ pcs)$  Basic dynamic load rating:  $C=45.7\ KN$  Basic static load rating:  $C_o=73.1\ KN$  Mass  $m_i=700kg$   $m_j=450kg$ 

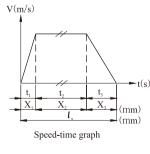
Mass  $m_i = 700kg$  Speed V = 0.75m/s

Time  $t_1 = 0.05s$   $t_2 = 1.9s$   $t_3 = 0.15s$ Acceleration  $a_1 = 15m/s^2$   $a_3 = 5m/s^2$ 

Travel Distance  $l_s = 1500 mm$ 

Distance  $l_1 = 650 \text{mm}$   $l_2 = 450 \text{mm}$   $l_3 = 135 \text{mm}$   $l_4 = 60 \text{mm}$   $l_5 = 175 \text{mm}$   $l_6 = 400 \text{mm}$ 





#### Load calculation of each block

At constant speed, the radial load  $P_n$ 

$$\begin{split} P_{i} &= \frac{m_{i}g}{4} - \frac{m_{i}g \cdot l_{i}}{2l_{i}} + \frac{m_{i}g \cdot l_{i}}{2l_{2}} + \frac{m_{2}g}{4} = 2562N \\ P_{2} &= \frac{m_{i}g}{4} + \frac{m_{i}g \cdot l_{i}}{2l_{i}} + \frac{m_{i}g \cdot l_{i}}{2l_{2}} + \frac{m_{2}g}{4} = 3987N \\ P_{i} &= \frac{m_{i}g}{4} + \frac{m_{i}g \cdot l_{i}}{2l_{i}} - \frac{m_{i}g \cdot l_{i}}{2l_{2}} + \frac{m_{2}g}{4} = 3073N \\ P_{i} &= \frac{m_{i}g}{4} - \frac{m_{i}g \cdot l_{i}}{2l_{i}} - \frac{m_{i}g \cdot l_{i}}{2l_{2}} + \frac{m_{2}g}{4} = 1648N \end{split}$$

Acceleration is toward left, the radial load  $P_n la_n$ 

$$\begin{split} P_{i}la_{i} &= P_{i} - \frac{m_{i} \cdot a_{i} \cdot l_{a}}{2l_{i}} - \frac{m_{2} \cdot a_{i} \cdot l_{s}}{2l_{i}} = -1577N \\ P_{2}la_{i} &= P_{2} + \frac{m_{i} \cdot a_{i} \cdot l_{a}}{2l_{i}} + \frac{m_{2} \cdot a_{i} \cdot l_{s}}{2l_{i}} = 8127N \\ P_{3}la_{i} &= P_{3} + \frac{m_{i} \cdot a_{i} \cdot l_{a}}{2l_{i}} + \frac{m_{2} \cdot a_{i} \cdot l_{s}}{2l_{i}} = 7212N \\ P_{4}la_{i} &= P_{4} - \frac{m_{i} \cdot a_{i} \cdot l_{a}}{2l_{i}} - \frac{m_{2} \cdot a_{i} \cdot l_{s}}{2l_{i}} = -2492N \end{split}$$

Lateral load Pt,la,

$$\begin{split} Pt_{l}la_{l} &= -\frac{m_{l}\cdot a_{l}\cdot l_{s}}{2l_{l}} = -485N \\ Pt_{l}la_{l} &= \frac{m_{l}\cdot a_{l}\cdot l_{s}}{2l_{l}} = 485N \\ Pt_{l}la_{l} &= \frac{m_{l}\cdot a_{l}\cdot l_{s}}{2l_{l}} = 485N \\ Pt_{s}la_{l} &= -\frac{m_{l}\cdot a_{l}\cdot l_{s}}{2l_{l}} = -485N \\ Pt_{s}la_{l} &= -\frac{m_{l}\cdot a_{l}\cdot l_{s}}{2l_{l}} = -485N \end{split}$$



#### Conditions of Use

Model: LSH30HL2X2520S20BP-M6(2 pcs) Basic dynamic load rating : C=45.7 KNBasic static load rating :  $C_0 = 73.1 \text{ KN}$ 

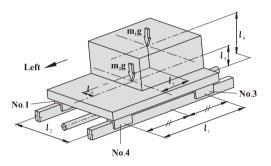
Mass  $m_1 = 700 kg$ m=450kg

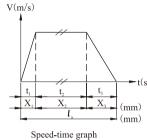
Speed V = 0.75 m/s

Time  $t_1 = 0.05s$  $t_1 = 1.9s$   $t_2 = 0.15s$ Acceleration  $a_1 = 15 m/s^2$  $a_3 = 5m/s^2$ 

Travel Distance  $l_s=1500mm$ 

Distance  $l_1 = 650 \text{mm}$   $l_2 = 450 \text{mm}$   $l_3 = 135 \text{mm}$   $l_4 = 60 \text{mm}$   $l_5 = 175 \text{mm}$ L=400mm





#### Load calculation of each block

Deceleration is toward left, the radial load  $P_n la_n$ 

$$P_1 l a_3 = P_1 + \frac{m_1 \cdot a_3 \cdot l_6}{2l_1} + \frac{m_2 \cdot a_3 \cdot l_5}{2l_2} = 3942N$$

$$P_2 la_3 = P_2 - \frac{m_1 \cdot a_3 \cdot l_6}{2l_1} - \frac{m_2 \cdot a_3 \cdot l_5}{2l_1} = 2607N$$

$$P_3 l a_3 = P_3 - \frac{m_1 \cdot a_3 \cdot l_6}{2l_1} - \frac{m_2 \cdot a_3 \cdot l_5}{2l_1} = 1693N$$

$$P_4 la_3 = P_4 + \frac{m_1 \cdot a_3 \cdot l_6}{2l_1} + \frac{m_2 \cdot a_3 \cdot l_5}{2l_2} = 3028N$$

Lateral load Pt,la3

$$Pt_{i}la_{3} = \frac{m_{i} \cdot a_{3} \cdot l_{4}}{2l_{i}} = 162N$$

$$Pt_2la_3 = -\frac{m_1 \cdot a_3 \cdot l_4}{2l_1} = -162N$$

$$Pt_3la_3 = -\frac{m_1 \cdot a_3 \cdot l_4}{2l} = -162N$$

$$Pt_{3}la_{3} = -\frac{m_{1} \cdot a_{3} \cdot l_{4}}{2l_{1}} = -162N$$

$$Pt_{4}la_{3} = \frac{m_{1} \cdot a_{3} \cdot l_{4}}{2l_{1}} = 162N$$

Acceleration is toward right, the radial load  $P_n ra_1$ 

$$P_{1}ra_{1}=P_{1}+\frac{m_{1}\cdot a_{1}\cdot l_{6}}{2l_{1}}+\frac{m_{2}\cdot a_{1}\cdot l_{5}}{2l_{1}}=6702N$$

$$P_2 r a_1 = P_2 - \frac{m_1 \cdot a_1 \cdot l_6}{2l_1} - \frac{m_2 \cdot a_1 \cdot l_5}{2l_1} = -152N$$

$$P_3 r a_1 = P_3 - \frac{m_1 \cdot a_1 \cdot l_6}{2l_1} - \frac{m_2 \cdot a_1 \cdot l_5}{2l_1} = -1067N$$

$$P_4 r a_1 = P_4 + \frac{m_1 \cdot a_1 \cdot l_6}{2l_1} + \frac{m_2 \cdot a_1 \cdot l_5}{2l_2} = 5787N$$

Lateral load Pt,ra,

$$Pt_{i}ra_{i} = \frac{m_{i} \cdot a_{i} \cdot l_{4}}{2l_{i}} = 485N$$

$$Pt_2ra_1 = -\frac{m_1 \cdot a_1 \cdot l_4}{2l_1} = -485N$$

$$Pt_3ra_1 = -\frac{m_1 \cdot a_1 \cdot l_4}{2l} = -485N$$

$$Pt_{3}ra_{i} = -\frac{m_{i} \cdot a_{i} \cdot l_{4}}{2l_{i}} = -485N$$

$$Pt_{4}ra_{i} = \frac{m_{i} \cdot a_{i} \cdot l_{4}}{2l_{i}} = 485N$$

Deceleration is toward right, the radial load  $P_n ra_3$ 

$$P_{1}ra_{3}=P_{1}-\frac{m_{1}\cdot a_{3}\cdot l_{6}}{2l_{1}}-\frac{m_{2}\cdot a_{3}\cdot l_{5}}{2l_{1}}=1183N$$

$$P_2 r a_3 = P_2 + \frac{m_1 \cdot a_3 \cdot l_6}{2l_1} + \frac{m_2 \cdot a_3 \cdot l_5}{2l_1} = 5367N$$

$$P_3 r a_3 = P_3 + \frac{m_1 \cdot a_3 \cdot l_6}{2l_1} + \frac{m_2 \cdot a_3 \cdot l_5}{2l_2} = 4452N$$

$$P_{j}ra_{j}=P_{j}+\frac{m_{l}a_{j}\cdot l_{b}}{2l_{l}}+\frac{m_{2}a_{j}\cdot l_{s}}{2l_{l}}=4452N$$

$$P_{s}ra_{j}=P_{s}-\frac{m_{l}a_{s}\cdot l_{b}}{2l_{l}}-\frac{m_{2}a_{j}\cdot l_{s}}{2l_{l}}=268N$$

Lateral load Pt,ra

$$Pt_{i}ra_{3} = -\frac{m_{i} \cdot a_{3} \cdot l_{4}}{2l_{i}} = -162N$$

$$Pt_2ra_3 = \frac{m_1 \cdot a_3 \cdot l_4}{2l_1} = 162N$$

$$Pt_3 ra_3 = \frac{m_1 \cdot a_3 \cdot l_4}{2l_1} = 162N$$

$$Pt_4 ra_3 = -\frac{m_1 \cdot a_3 \cdot l_4}{2l_1} = -162N$$

#### **Equivalent load calculation**

At constant speed

$$P_{EI} = P_I = 2562N$$

$$P_{E2} = P_2 = 3987N$$

$$P_{E3} = P_3 = 3073N$$

$$P_{Ed} = P_d = 1648N$$

When acceleration is toward left

$$P_{\scriptscriptstyle E_I} la_{\scriptscriptstyle I} = |P_{\scriptscriptstyle I} la_{\scriptscriptstyle I}| + |Pt_{\scriptscriptstyle I} la_{\scriptscriptstyle I}| = 2062N$$

$$P_{E2}la_1 = |P_2la_1| + |Pt_2la_1| = 8611N$$

$$P_{E3}la_1 = |P_3la_1| + |Pt_3la_1| = 7697N$$

$$P_{E_4}la_1 = |P_4la_1| + |Pt_4la_1| = 2976N$$



#### **Conditions of Use**

 $\label{eq:model:LSH30HL2X2520S20BP-M6(2 pcs)} \mbox{Basic dynamic load rating}: C=45.7 \ KN \\ \mbox{Basic static load rating}: C_{\theta}=73.1 \ KN \\ \mbox{Model}$ 

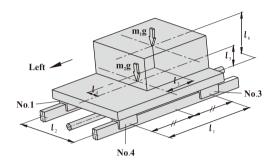
 $Mass m_1 = 700kg m_2 = 450kg$ 

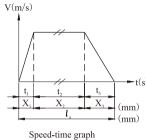
Speed V=0.75m/s

Time  $t_1 = 0.05s$   $t_2 = 1.9s$   $t_3 = 0.15s$ Acceleration  $a_1 = 15m/s^2$   $a_3 = 5m/s^2$ 

Travel Distance L=1500mm

Distance l = 650 mm l = 450 mm l = 135 mm l = 60 mm l = 175 mm l = 400 mm





#### Equivalent load calculation

When deceleration is toward left

$$P_{E_1} la_3 = |P_1 la_3| + |P_1 la_3| = 4104N$$

$$P_{F}, |a_{3}| = |P, |a_{3}| + |Pt, |a_{3}| = 2769N$$

$$P_{E_3}la_3 = |P_3la_3| + |Pt_3la_3| = 1854N$$

$$P_{E_4}la_3 = |P_4la_3| + |Pt_4la_3| = 3189N$$

When acceleration is toward right

$$P_{E_i} r a_i = |P_i r a_i| + |P t_i r a_i| = 7186N$$

$$P_{E2}ra_1 = |P_2ra_1| + |Pt_2ra_1| = 637N$$

$$P_{E_3}ra_1 = |P_3ra_1| + |Pt_3ra_2| = 1551N$$

$$P_{Ed}ra_I = |P_dra_I| + |Pt_dra_I| = 6272N$$

When deceleration is toward right

$$P_{E_1}ra_3 = |P_1ra_3| + |Pt_1ra_3| = 1344N$$

$$P_{F}, ra_{3} = |P_{3}, ra_{3}| + |Pt_{3}, ra_{3}| = 5529N$$

$$P_{E3}ra_3 = |P_3ra_3| + |Pt_3ra_3| = 4614N$$

$$P_{E_4} r a_3 = |P_4 r a_3| + |P_4 r a_3| = 430N$$

#### Calculation of static safety factor

We now know that the maximum equivalent load occurs on No.2 slider. Therefore, one can calculate static safety factor based on it in following formula

$$f_s = \frac{C_0}{P_{E,2}la_1} = \frac{73.1 \times 10^3}{8611} = 8.49$$

#### Calculation of the average load of each slider $P_{mn}$

$$P_{mi} = 3\sqrt{-(P_{Ei}la_{i}^{3}X_{i} + P_{Ei}^{3}X_{2} + P_{Ei}la_{j}^{3}X_{3} + P_{Ei}ra_{j}^{3}X_{1} + P_{Ei}^{3}X_{2} + P_{Ei}ra_{j}^{3}X_{3})} - \frac{1}{2l_{i}}$$

=2701N

$$P_{m2} = 3\sqrt{\frac{(P_{E2}la_1^3X_1 + P_{E2}^3X_2 + P_{E2}la_3^3X_3 + P_{E2}ra_1^3X_1 + P_{E2}^3X_2 + P_{E2}ra_3^3X_3)}{2l_s}}$$

=4077N

$$P_{m3} = 3\sqrt{\frac{(P_{E3}la_{i}^{3}X_{i} + P_{E3}^{3}X_{2} + P_{E3}la_{j}^{3}X_{3} + P_{E3}ra_{i}^{3}X_{i} + P_{E3}^{3}X_{2} + P_{E3}ra_{j}^{3}X_{3})}{2l_{i}}}$$

=3188N

$$P_{md} = 3 \sqrt{ \frac{(P_{Ed} la_1^3 X_1 + P_{Ed}^3 X_2 + P_{Ed} la_3^3 X_3 + P_{Ed} ra_1^3 X_1 + P_{Ed}^3 X_2 + P_{Ed} ra_3^3 X_3)}{2l_s}}$$

=1873N

#### Calculation of rated life $L_n$

Assuming  $f_w$ =1.5 and according to rated life formula, the rated life can be calculated as follows:

$$L_i = \left(\frac{C}{f.P.L.}\right)^3 \times 50 = 71758Km$$
  $L_3 = \left(\frac{C}{f.P.L.}\right)^3 \times 50 = 43641Km$ 

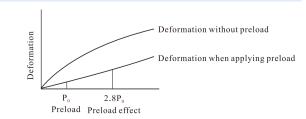
$$L_{2} = \left(\frac{C}{f_{w}P_{m2}}\right)^{3} \times 50 = 20865Km \qquad L_{4} = \left(\frac{C}{f_{w}P_{m4}}\right)^{3} \times 50 = 215195Km$$

#### Calculation conclusion

Choose the minimum from four sliders to represent rated life, which is 20865 Km on No.2 slider

#### Preload and rigidity

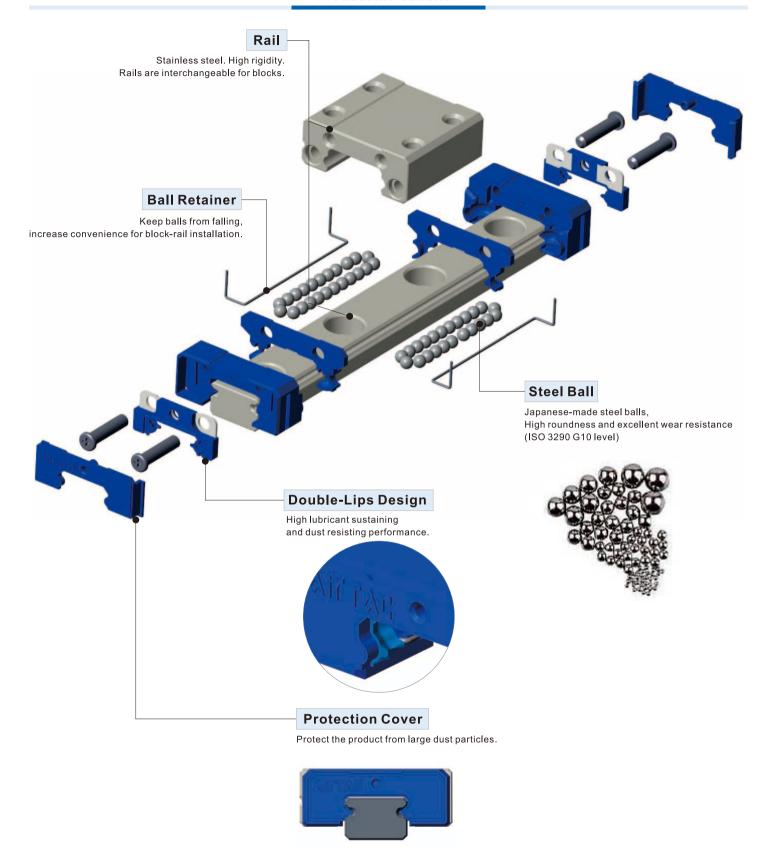
Preload spec can be applied to enhance rigidity. As the graph shows on the right, the effectiveness of preload can maintain until external load reaches 2.8 times of preload strength. In other words, rigidity increases 2.8 times. Preload is applied by choosing bigger diameter of rollers to increase interference between rollers and groove and raise initial loads. Therefore when calculating rated life, preload should be put into consideration.



# A

## LRM Series Miniature Linear Guide

#### **Product Introduction**



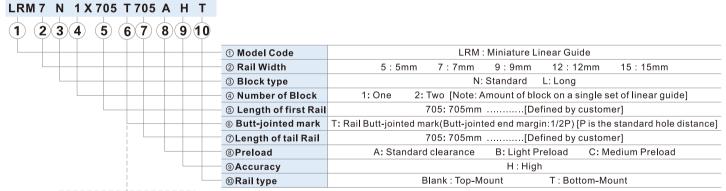




#### Order Information(Combined)

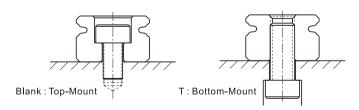
#### LRM 7 N 1 X40 S5 A H T **(1) (2) (3) (4) (5) (6) (7) (8) (9)** ① Model Code LRM: Miniature Linear Guide ② Rail Width 9:9mm 12:12mm 5 : 5mm 7:7mm15:15mm 3 Block type N: Standard L: Long 2: Two [Note: Amount of block on a single set of linear guide] 1: One **4 Number of Block** [Refer to rail spec. table for detail] **⑤ Rail Length** 40: 40mm..... S : Distance from end of rail to the center of first mounting hole. **®Position of first** (It is recommended to be greater than minimum edge) mounting hole [Refer to rail spec table for details] B: Light Preload C: Medium Preload A: Standard clearance ⑦ Preload P : Precision H: High **® Accuracy** T: Bottom-Mount Rail type Blank: Top-Mount

#### **Butt-jointed Order Information**



Butt-jointed end margin: 1/2P, Position of the first and last hole is defined by customer. [Note 1] Allow only two rails for standard joint. Customization is needed for more than two rails.

[Note 2] Customization is needed if the first/last mounting hole position is out of range in 'Rail Specification Table'.





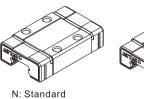
#### 1. Block Order Information

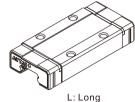
# LRM 7 BK-N-H-D (1) (2) (3) (4) (5) (6)

Notes: 1. When selecting rails and bearings, the different pairing codes can change the units preload, details see "preload pairing chart".

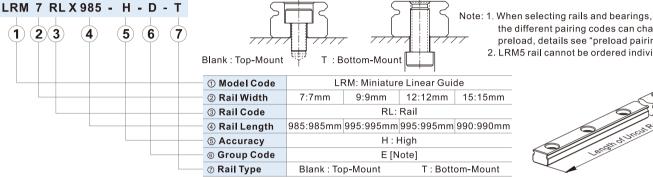
2. LRM5 block cannot be ordered individually.

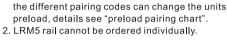
① Model Code	LRM : Miniature Linear Guide		
② Rail Width	7:7mm 9:9mm 12:12mm 15:15mm		
③ Block Code	BK: Block		
BlockType	N: Standard L: Long H : High		
⑤ Accuracy			
6 Group Code	B C D E[Note]		

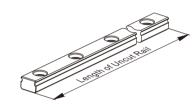




#### 2. Uncut Rail Order Information





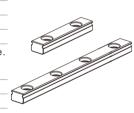


#### 3. Rail Order Information

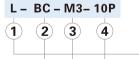


Note: 1. When selecting rails and bearings, the different pairing codes can change the units preload, details see "preload pairing chart'

(4) (0)(0) (4) (5) (0) (7) (0)	cannot be ordered individually.
① Model Code	LRM: Miniature Linear Guide
② Rail Width	7:7mm 9:9mm 12:12mm 15:15mm
③ Rail Code	RL: Rail
4 Rail Length	40: 40mm [Refer to rail spec. table for detail]
⑤ Position of first mounting hole	S : Distance from end of rail to the center of first mounting hole.  (It is recommended to be greater than minimum edge)  [Refer to rail spec table for details]
® Accuracy	H: High
<b>⊘Group Code</b>	E[Note]
® Rail Type	Blank : Top-Mount T : Bottom-Mount

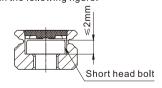


#### 4. Accessory (Bolt hole plug) Order Code



- 1. Bolt hole plugs are packed in one bag per 10pcs. EX: When ordering 1pc of "L-BC-M3-10P", it comes with 10pcs plugs;
- 2."L-BC-M3-10P" is applied to LRM9/12/15 series;
- 3. When mounting plugs for LRM9 series, short head bolts are required, bolt size is shown in the following figure.

<b>①Accessories</b>	L: Linear Guide Accessory
②Plug Code	BC: Bolt hole plug
③Plug Specification	M3: Used for M3 bolt
<b>@Plug quantity</b>	10P: 10pcs/bag



#### 5. Rail/Block preload pairing chart

When customer orders rail/block, please choose the pairing code of rail/block in accordance with the needed preload of linear guide(combined). Details please refer to the "preload pairing chart".

	LRM7、LRM9 Preload pairing char			
Preload		ad	Rail pairing code	
	grade	Э	E	
	District	В	-	
	Block pairing code	С	Medium preload	
		D	Light preload	
		Е	Standard clearance	

LRM12 LRM15 Preload pairing chart				
Preload grade		Rail pairing code		
		E		
Divi	В	Medium preload		
Block pairing code	С	Light preload		
	D	-		
	Е	Standard clearance		

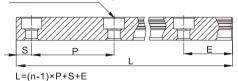




#### **Rail Specification**

The edge pitch of first mounting hole (S) and last mounting hole (E) should not be greater than 1/2P. Overlong edge may induce unstable installation and affect the accuracy.

n: Numbers of mounting holes



- L: Total length of rail(mm)
- L. Total length of fall(lilli)
- n: Numbers of mounting holes on rail
- P: Distance between bolt holes(mm)
- S: Edge of first mounting hole(mm)
- E: Edge of last mounting hole(mm)

Model	Maximum length(L max)(mm)
LRM5	490
LRM7	985
LRM9	995
LRM12	995
LRM15	990

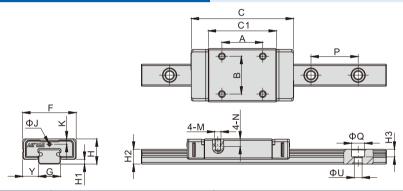
Model	Pitch(P)	Standard Edge pitch	Min. Edge Pitch (S/E min)	Max. Edge Pitch (S/E max)
LRM5	15	5	3	10
LRM7	15	5	3	10
LRM9	20	7.5	4	15
LRM12	25	10	4	20
LRM15	40	15	4	35

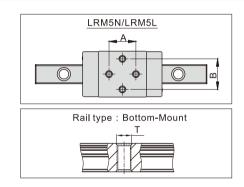
Note: •Joint rail must be chosen if length of rail exceeds the maximum.

• When deciding edge pitch, it should be within the range of above table.

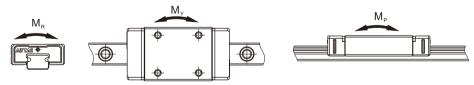
There would be risk of broken hole if pitch is out of range.

#### **Specifications and Dimensions**





Model\Item	External Dimension ( mm )				Block Dimension ( mm )					Rail Dimension ( mm )									
Model/Itelli	Н	H1	F	Υ	С	C1	Α	В	М	N	K	ΦЈ	G	H2	Р	ΦQ	ΦU	НЗ	Т
LRM5N	6	1.5	12	3.5	18.2	10	7	8	M2X0.4	1.5	1.3	0.7	5	3.5	15	3.5	2.2	1.1	M3X0.5
LRM5L	6	1.5	12	3.5	21.2	13	7	8	M2X0.4	1.5	1.3	0.7	5	3.5	15	3.5	2.2	1.1	M3X0.5
LRM7N	8	1.5	17	5	24.3	13.5	8	12	M2X0.4	2.3	1.7	0.7	7	4.7	15	4.2	2.4	2.4	M3X0.5
LRM7L	8	1.5	17	5	32.5	21.7	13	12	M2X0.4	2.3	1.7	0.7	7	4.7	15	4.2	2.4	2.4	M3X0.5
LRM9N	10	2	20	5.5	31	18.9	10	15	M3X0.5	2.8	2.2	1	9	5.6	20	6	3.5	3.4	M4X0.7
LRM9L	10	2	20	5.5	42.1	30	16	15	M3X0.5	2.8	2.2	1	9	5.6	20	6	3.5	3.4	M4X0.7
LRM12N	13	3	27	7.5	37.6	21.7	15	20	M3X0.5	4	3	1.5	12	7.5	25	6	3.5	4.4	M4X0.7
LRM12L	13	3	27	7.5	48.4	32.5	20	20	M3X0.5	4	3	1.5	12	7.5	25	6	3.5	4.4	M4X0.7
LRM15N	16	3.5	32	8.5	48	28	20	25	M3X0.5	4	3.7	М3	15	9.5	40	6	3.5	4.4	M4X0.7
LRM15L	16	3.5	32	8.5	65	45	25	25	M3X0.5	4	3.7	М3	15	9.5	40	6	3.5	4.4	M4X0.7

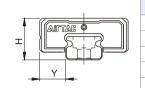


Model\Item	Mounting	Dynamic Load Rating(kN)	Static Load Rating(kN)	Static R	ated Mome	nt (N.m)	Wei	ght
Model/Item	Screw	C <sub>100B</sub>	C <sub>o</sub>	$M_{R}$	M <sub>P</sub>	$M_{\scriptscriptstyle Y}$	Block(kg)	Rail(kg/m)
LRM5N	M2	0.33	0.55	1.68	0.99	0.99	0.0035	0.114
LRM5L	M2	0.48	0.9	2.4	2.08	2.08	0.004	0.114
LRM7N	M2	1.02	1.53	5.42	3.17	3.17	0.009	0.22
LRM7L	M2	1.43	2.45	9.27	7.96	7.96	0.014	0.22
LRM9N	М3	1.97	2.6	11.84	8.19	8.19	0.018	0.315
LRM9L	М3	2.61	4.11	19.73	18.94	18.94	0.027	0.315
LRM12N	М3	3.04	3.86	23.63	12.57	12.57	0.037	0.602
LRM12L	М3	3.96	5.9	40.96	32.57	32.57	0.053	0.602
LRM15N	М3	4.27	5.7	45.05	23.05	23.05	0.054	0.981
LRM15L	М3	6.53	9.53	70.08	63.69	63.69	0.088	0.981



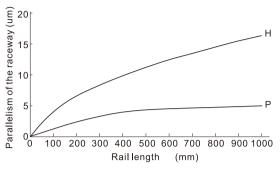
#### **Accuracy**

LRM miniature linear guide comes with 2 accuracy levels.



Accuracy Star	( <b>mm</b> )	
Accuracy	H: High	P:Precision
Tolerance of height H	±0.02	±0.01
Variation of height $\Delta H$	0.015	0.007
Tolerance of width Y	±0.025	±0.015
Variation of width $\Delta Y$	0.02	0.01

Parallelism of motion relative to benchmark surface.



#### **Preload Level**

LRM Miniature Linear Guide has three preload categories: A,B and C.

Choosing suitable preload level will enhance rigidity, precision and torsion resistant performace of the linear guide.

Preload Level	Cada	Code Radial interference					Application	
Preioad Level	Code	5	7	9	12	15	Application	
Standard clearance	Α	-1~+2	-2~+2	-2~+2	-2~+3	-2~+3	Smooth operation	
Light Preload	В	-3~-1	-4~-2	-5~-2	-6~-2	-7~-2	High Precision	
Medium Preload	С	-6~-2	-7~-3	-8~-4	-9~-5	-10~-6	High rigidity	

#### **Load Capacity and Rating Life**

#### 1. Basic static load rating(C<sub>0</sub>)

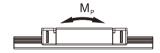
It is defined as the static load when the total permanent deformation of the steel ball and the surface of the groove is exactly one ten-thousandth of the diameter of the steel ball under the state of the load direction and size unchanged.

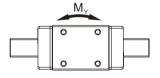
#### 2. Static Permissible Moment(M<sub>0</sub>)

When the steel ball subjected to the maximum stress in the slider reaches a static rated load condition, this loading moment is called the

"Static permissible moment". The definition comes in three directions.







#### 3. Static Safety Factor(f<sub>s</sub>)

Impact, vibration and inertial loading during start and stop moment lead to unexpected load on the linear guide way.

Therefore, when calculating the static load, safety factors must be considered.

Load Condition	f <sub>s</sub>
Normal Load	1.0~2.0
Load with Impacts or Vibrations	2.0~3.0

$$f_s = \frac{C_0}{P} = \frac{M}{M}$$

f<sub>s</sub> : Static safety factor

 $C_0$ : Basic static load rating (N)

 $M_{\scriptscriptstyle 0}$ : Static permissible moment (N.m)

P : Calculated working load (N)

M : Calculated applying moment (N.m)

#### 4. Load Factor(f<sub>w</sub>)

The loads acting on a linear guide way include the weight of block, the inertia load at the times of start and stop, and the moment loads caused by overhanging. Therefore, the load on a linear guide way should be divided by the empirical factor.

Loading condition	Service speed	f <sub>w</sub>
No impacts & vibration	V≤15m/min	1~1.2
Small impacts	15m/min <v≤60m min<="" td=""><td>1.2~1.5</td></v≤60m>	1.2~1.5
Normal load	60m/min <v≤120m min<="" td=""><td>1.5~2.0</td></v≤120m>	1.5~2.0
With impacts & vibration	V>120m/min	2.0~3.5

#### 5. Dynamic Load Rating(C<sub>100B</sub>)

C<sub>1008</sub>: (According to ISO 14728-1) As the direction and magnitude remains the same, C<sub>1008</sub> is the maximum workload for the product to maintain its nominal life at 100km of operation.

## AITTAL

#### LRM Series

#### 6. Calculation of Nominal Life(L)

Recognizing that nominal life of a linear guide is affected by the actual working loads, the general calculation of the nominal life excluding the environmental factors is carried out as follow:

$$L = \left(\frac{C_{100B}}{f_w x P}\right)^3 x 10^5$$

. = Nominal Life (r

 $C_{100B}$ = Dynamic Load Rating (N)

f<sub>w</sub>: Load Factor

P =Equivalent load (N)

Taking LRM9N for example, its  $C_{\tiny{100B}}$  is 1.97kN. Therefore, when the product bears a 1.5kN equivalent load P.  $f_{\tiny{w}}$ =1,

its theoretical rated life can be calculated as follows:

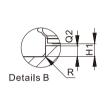
$$L = \left(\frac{C_{1008}}{f_w x P}\right)^3 x 10^5 = \left(\frac{1.97}{1 x 1.5}\right)^3 x 10^5 = 226529 \text{ m} = 226.5 \text{ km}$$

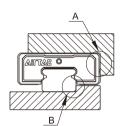
#### Installation Illustration

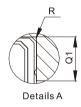
#### 1 Height and Chamfer of Reference Edge

In order to ensure accurate installation of LRM Linear Guide, the contact space should not exceed the given figures in following table.

			l	Jnit : mm
Model	Q1	Q2	H1	R(Max)
LRM5	2	1.2	1.5	0.2
LRM7	3	1.2	1.5	0.2
LRM9	3	1.7	2	0.3
LRM12	4	2.7	3	0.4
LRM15	5	3.2	3.5	0.5





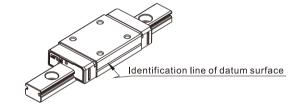


#### 2. Screw Tighten Torque

Model	Screw	Tighten Torque(N.cm)						
woder	size	Iron	Casting	Aluminum alloy				
LRM5	M2	58.8	39.2	29.4				
LRM7	IVIZ	50.6	39.2	29.4				
LRM9								
LRM12	МЗ	196	127	98				
LRM15								

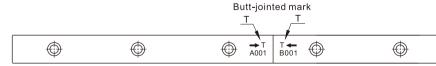
#### 3. Datum plane

- Datum plane for installation must be ground or finely milled to ensure accuracy.
- Both sides of rail can be used as the datum plane.
- For multi-blocks on a rail, identification line on blocks should be put on the same side to ensure moving accuracy.

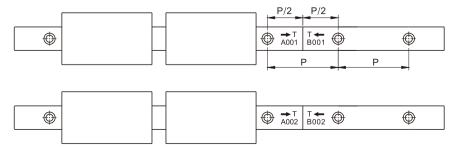


#### Rail Butt-jointed

When jointing rails, it must follow group marks on rail to ensure the accuracy of linear guide.
 These marks are located on the top surface at joint side. Please put the same group marks together.



- ullet Be aware serial number of group mark when assemble. A001 and B001 are in a group, so as to A002 and B002 and so on.
- Be aware the installation direction while assembly, the serial numbers are not upside down and arrows point to each other.





#### **Lubrication Method**

When a linear guide is well lubricated, it can reduce wear and increase lifespan significantly. Lubrication has the following benefits:

- Reduces friction of the rollers and rail to minimize wear.
- The grease film between contact surface can decrease the fatigue failure.
- Prevent rust.

#### 1. Lubrication method

LRM series linear guide is well lubricated with 'Synergy Grease PS NO.2' in factory. Customers are recommended to use identical or the same grade of lubricant.

Please refer to the right table for the amount of oil:

In order to be well lubricated, the blocks need to be moved back and forth after lubricating.

Lubrication can be done either by manual or automatic device.

#### 2. Lubrication frequency

Although the linear guides are well lubricated at the factory and retains grease well, frequent lubrication is still necessary to avoid undesirable wear.

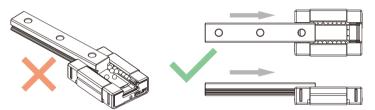
Recommended lubrication period is every 100km of movement or every 3~6 months. (Refer to table on the right for suggested amount).

Model	Initial lubrication (cm³)	Replenishment amount (cm³)
LRM5N	0.02	0.01
LRM5L	0.03	0.015
LRM7N	0.1	0.05
LRM7L	0.13	0.07
LRM9N	0.2	0.1
LRM9L	0.28	0.14
LRM12N	0.34	0.17
LRM12L	0.45	0.23
LRM15N	0.72	0.36
LRM15L	1.0	0.50

#### Precautions on use

#### 1. Block disassembly

LRM is equipped with ball retainers to prevent steel balls from falling out when block separates from rail. However, if obliquely insert rail into blocks or quickly assemble and disassemble, there is risk for steel balls of falling out. Please carefully assemble the linear guide or use plastic rails to assist.



#### 2. Caution

- Parts may slide out if linear guide is put unevenly. Please be careful.
- Hitting or dropping a linear guide could have huge effects on accuracy and lifespan even though appearance may remain intact. Please be careful.
- Do not separate linear guide as external objects may enter blocks and cause accuracy problem.

#### 3. Lubrication

- Linear guide have been treated with anti-rust oil during production. Before use, wipe the rail and treat it with lubrication.
- Do not mix lubricating oil (grease) with different properties.
- While lubricating, the block needs to be moved back and forth. After lubrication, there should be a grease film on rail.

#### 4. Use

- The operating environment temperature should not exceed 80°C, and the maximum temperature should not exceed 100°C.
- Do not separate blocks from rail whenever it is not necessary. If you need to separate them, please use plastic rails to prevent steel balls from falling out.

#### 5. Storage

When storing blocks, rails or set, please be sure that anti-rust oil is well applied and product is well sealed as well as placed horizontally.
 Avoid humidity and high temperatures environment.

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